First operational results of RELASE (Rainfall Estimation from Lightning And SEviri data) software at CNMCA

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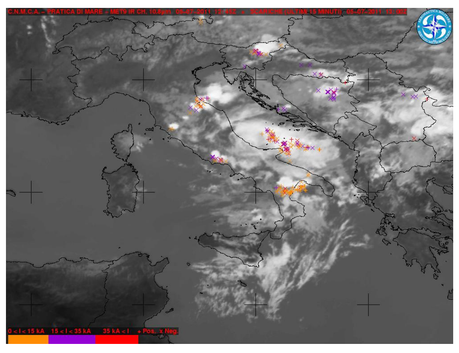
ABSTRACT

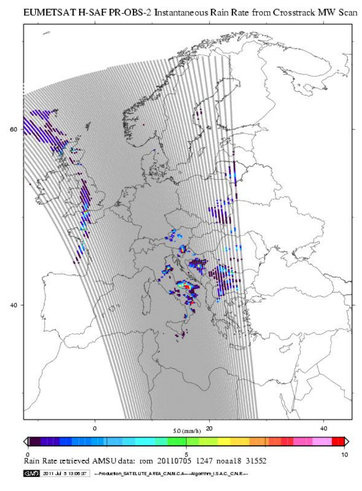
For the next generation of geostationary meteorological satellites (Meteosat Third Generation - MTG) an optical Lightning Imager (LI) mission is planned. Together with the GLM (Geostationary Lightning Mapper), that will be flown on the next generation of GOES (Geostationary Operational Environmental Satellite) series, there will be an almost global coverage for lightning detection from space. These continuous flow of lightning data will be crucial and critical in many applications as in nowcasting, climatology and atmospheric research. The collaboration between CNMCA (Centro Nazionale di Meteorologia e Climatologia Aeronautica - Italy) and SELEX-GALILEO (a Finmeccanica company) aims to study a possible use of lightning data in hydrological field. A rainfall retrieval technique that use geostationary satellite Infrared (IR) observations and lightning information retrieved from LAMPINET (lightning network of the Italian Air Force Meteorological Service) is presented in this paper. A comparison with products of HSAF (EUMETSAT Satellite Application Facility on Support to Operational Hydrology and Water Management) is also presented.

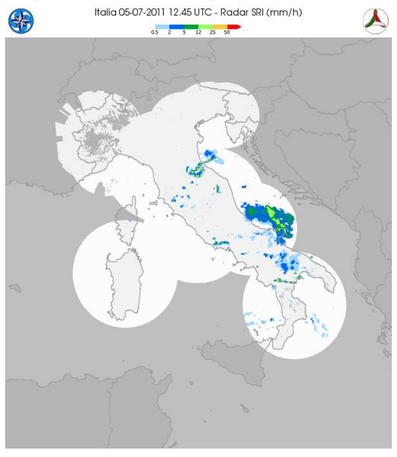
Data sources



Italian Air Force Meteorological Service set up a lightning network and put it in operation during 2004. The network is based on Vaisala technology with 15 IMPACT ESP sensors distributed on the peninsula and islands. Performances of the network can reach a detection efficiency of 90% and location accuracy of 0,5 km all over Italian area.
Brightness temperature of SEVIRI channel 9 (10.8 μm) is processed straight from HRIT raw files.

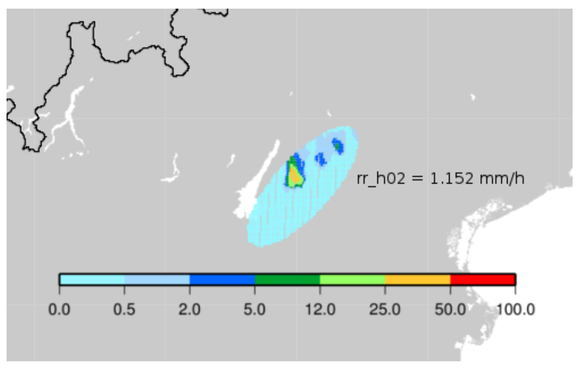
H02 PR-OBS-2 is based on the instruments AMSU-A and AMSU-B or MHS flown on NOAA and MetOp satellites. These cross-track scanners provide images with constant angular sampling across track: IFOV elongates as the beam moves from nadir toward the edge of the scan . The elongation is such that:
• for AMSU-A IFOV at nadir is: 48X48 Km^2, at the edge of the 2250 Km swath: 80X150 Km^2
• for AMSU-B and MHS IFOV
at nadir is: 16X16 Km^2; at the edge: 27X50 Km^2.
Since the incidence angle changes moving cross-track, the effect of polarisation also changes, and various frequencies are observed in a single polarisation, V or H. Algorithms are developed by C.N.R.- I.S.A.C.





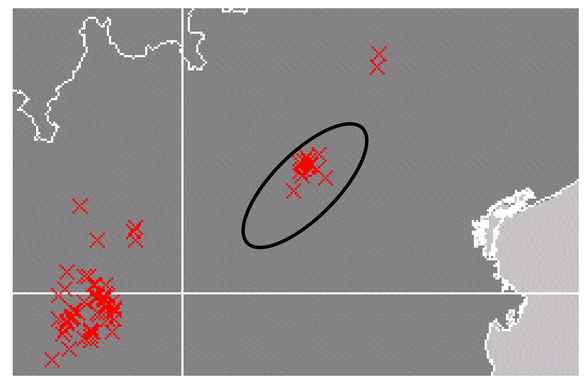
Currently, the National Radar Network is composed of 21 radar that work in the C band. The volume made available from each site, with a frequency of at least 15 minutes, is preprocessed according to a set of techniques to de-clutter and resampled at a resolution of 1km. The product of SRI calculates the precipitation to the ground by applying an algorithm on volumetric data of the PPI reflectivity at lower elevation between those acquired which meet the quality criteria in the planning stage. The reflectivity values are converted to measure precipitation (rain rate mm/h) according to the Marshall Palmer equation ($Z = aR^b$) with a = 200 and b = 1.6.

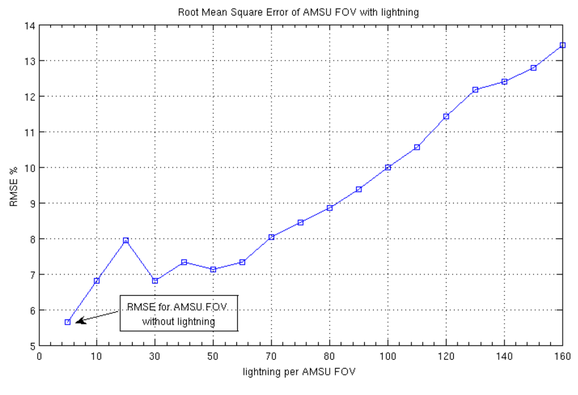
Lightning and rainfall estimation from space



One of the objectives of the “EUMETSAT Satellite Application Facility on Support to Operational Hydrology and Water Management (H-SAF) is to provide new satellite-derived products from existing and future satellites with sufficient time and space resolution to satisfy the needs of operational hydrology. Polar satellites alone present some problems to identify convective rain because of their low temporal resolution and narrow area of observation. It's even possible that a severe storm can start and finish between two passages of satellites. In the figure on the left there is a comparison between precipitation retrieval by microwave sensor on polar satellite (AMSU, elliptical footprint) and radar (with colour scale). Below there is the electrical activity in the same area. The convective precipitation is almost entirely seen.

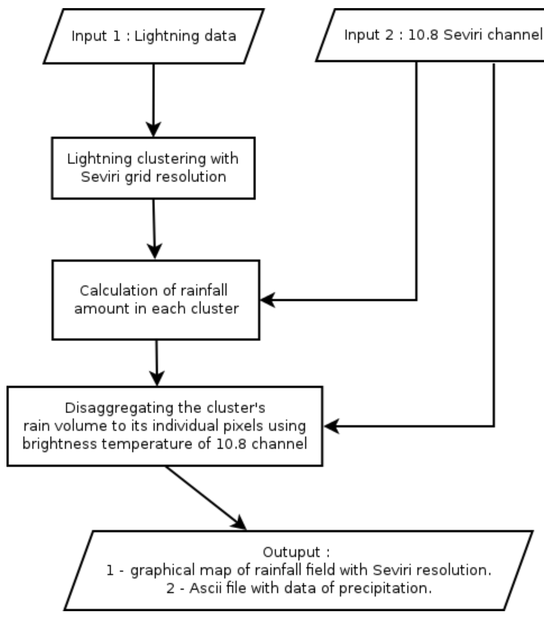
A dataset composed by 27 days of gathered data (radar rainfall rate, 10.8 μm Seviri images, LAMPINET data, PR-OBS-2 precipitation rate at ground) from 3rd March 2011 to 30th June 2011 is been used. After different processes of upscaling it has been possible a comparison between rainfall rate from radar and AMSU in presence or not of electrical activity. In the figure below RMSE raises up to 13.5% with the increasing of number of lightning. When lightning aren't present RMSE is about 5.5%





On the other hand geostationary satellites offer a better spatial e temporal resolution but sensors onboard (in the visible and infrared) are not the best to retrieve precipitation. Therefore lightning detection, and the correlation between number of lightning and rainfall, can be very useful to improve satellite retrieval of precipitation both from polar and geostationary satellite.
For this purpose a software named RELASE (Rainfall Estimation from Lightning And Seviri data) has developed at CNMCA.

RELASE (Rainfall Estimation from Lightning And Seviri data)

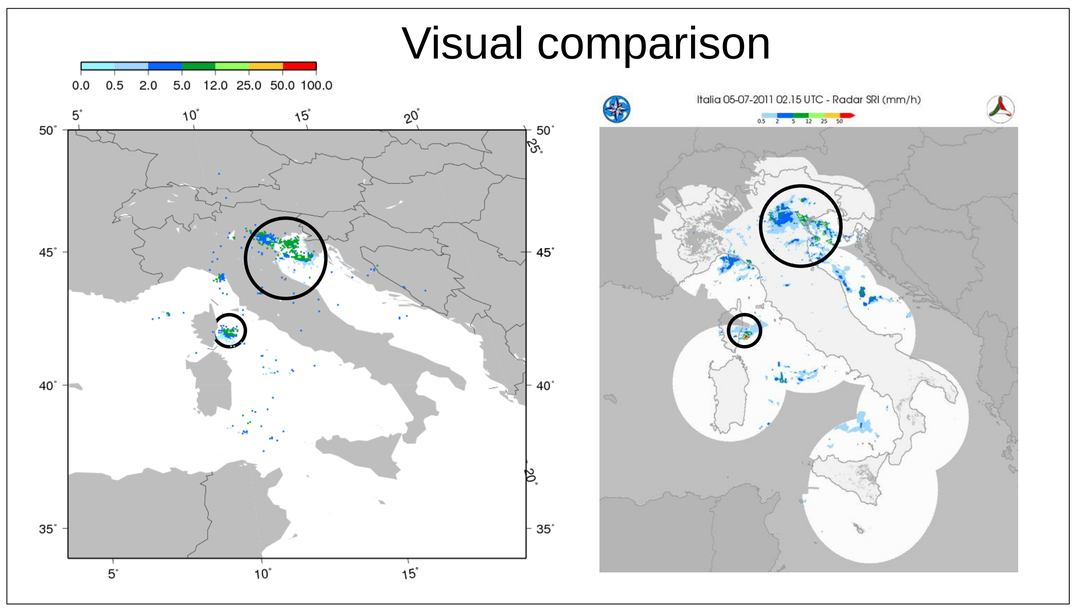


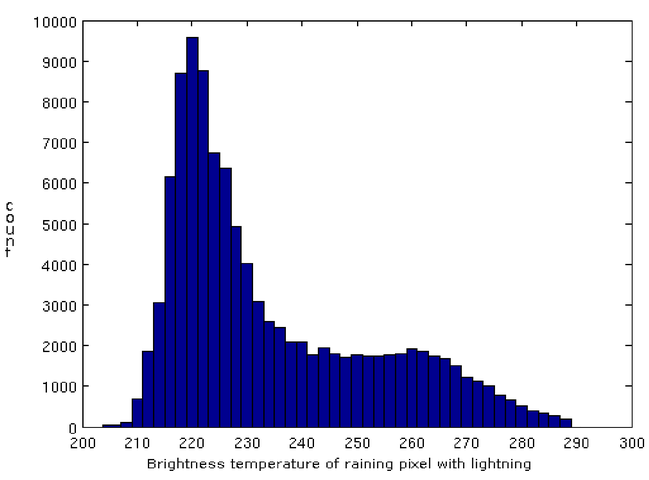
Flux diagram of the software is in figure on the left.
To determine a quantitative relationship for rainfall estimation using lightning and Seviri data a bivariate linear regression for the cluster's rain volume has been employed:

$$RR = \left(b_0 + b_1 \cdot \frac{S}{N} + b_2 \cdot T\right) N$$

where RR is the cluster's rain volume in mm h^{-1} km^2 (from Italian weather radar network), S is the number of the flashes (from Lampinet), T in K is the minimum 10.8 μm brightness temperature in the cluster and N is the number of pixels in the cluster. The coefficients b_0 , b_1 , and b_2 are determined using a least squares regression.
To disaggregate the cluster's rain volume to its individual pixel, the histogram of the IR temperature (constructed from all pixels associated with lightning that exist in the dataset) has been used (Figure below).

Visual comparison





The probabilities :
P(T) = P(a raining pixel has temperature > T)
is calculated from the histogram. The disaggregation procedure uses these IR temperature probabilities to compute weights for each individual pixel of a convective cluster. A pixel’s weight is defined as the ratio of the pixel’s probability to the sum of probabilities of all pixels located within the same convective cluster. The proposed combined IR–lightning algorithm for convective rainfall estimation can be summarized as follows:

1. **read an IR image (software can read HRIT seviri raw format directly);**
2. **determine the lightning strikes within a 15 minutes window, centred around the IR sampling time;**
3. **determine the lightning clusters;**
4. **determine the rain volume of each cluster with the equation above;**
5. **allocate the rain volume of each cluster to pixels based on histogram and probability written above;**

Results and conclusions

Dataset is composed by 27 days of gathered data (radar rainfall rate, 10.8 μm Seviri images, LAMPINET data) from 3rd March 2011 to 30th June 2011. In each of these days there are multiple storms. Dataset contains 4703 lightning's clusters. This dataset has been used for the calibration of software (i.e. least squares regression to determinate the coefficients b_0 , b_1 , and b_2). The mean values of parameters identified by this calibration are b_0 = 0.5131, b_1 = 0.2373 and b_2 = -0.0014.
From 1st July RELASE is in operative chain at CNMCA and works h24. In this first period of evaluation, to characterize statistically the agreement between radar rainfall rate (considered as “true” value) and lightning observations three performance scores has been used: the probability of detection (POD), the false alarm rate (FAR), and the critical success index (CSI), defined as

$$POD = \frac{n_{success}}{n_{success} + n_{failure}} \qquad FAR = \frac{n_{falsealarm}}{n_{success} + n_{falsealarm}} \qquad CSI = \frac{n_{success}}{n_{success} + n_{falsealarm} + n_{failure}}$$

where $n_{success}$, $n_{failure}$ and $n_{false\ alarm}$ are the numbers of successes, failures, and false alarms, respectively, in the comparison. A comparison yields a success when there is lightning and a radar rainfall rate greater than 10 mm/h, a false alarm when there is lightning but not rainfall, and a failure when there is rainfall greater than 10 mm/h with no lightning indications.
The software has been tested on 873 lightning's clusters and the results are:
POD = 0.48
FAR = 0.34
CSI = 0.30
The general conclusion of this study is that lightning data contain useful information for satellite rainfall estimation, mainly in convective phenomena where MW retrieval can presents some problems. Good scores of RELASE software suggests a possible use as product in HSAF project to improve rainfall estimation of MW and IR techniques. **In future RELASE will tested with LI and after a calibration period it will be able to work with the sensor data.**

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